

Get customized control

with the best value at optimum size

SHOWN AT ACTUAL SIZE - 128 mm (5.04 in.

The SYSDRIVE JV Series of Micro Inverters delivers precise control without compromising panel space or your budget.



Multi-function I/O support

- Supports analog inputs of 0 to 10V, 4 to 20 mA, or 0 to 20 mA
- · Supports an analog monitor output and a digital output
- Accepts both PNP and NPN inputs

Protection for your machinery

- A high-speed current limiting function minimizes over-current trips (above 250% of rated current)
- · Quick restarts after momentary power loss
- · Stall prevention and fault retry functions
- Overtorque detection
- · UL recognized electronic thermal overload
- Inrush current suppression and ground fault protection

Easy to install and maintain

- Optional DIN-rail bracket for guick rail mounting
- · Space-saving design ideal for new or retrofit panels
- Easily mounted cooling fan can be adjusted to run only when the JV is running

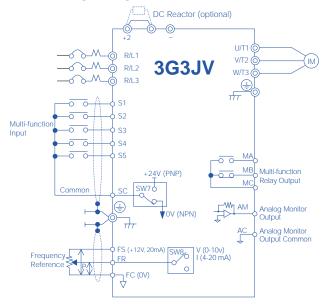
Easy to setup and program

- Integrated, face-mounted speed potentiometer for quick start up after power is applied
- Quick-start LEDs for easy programming
- Communication options include RS-232C/485
- Multi-step speed control for up to nine steps, UP/DOWN operation, and jog operation

Outstanding price/performance relationship

- Ideal for simple, low horsepower speed control applications
- Excellent starting torque of 150% at 3Hz
- · Virtually immune to overload
- Consistent performance despite changing conditions
- Full-range automatic torque boost
- Slip compensation

Wiring Diagram



Note: Connect single-phase 230 VAC to terminals R/L1 and S/L2 of the $3G3JV-AB\square$.







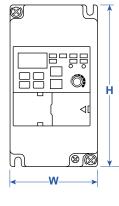
Specifications

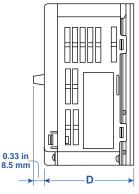
| Voltage Class | | | | 230 VA | C single- | /3-nhase | | | | | 460 VAC | 3-nhase | | | |
|--------------------------------|--|--|--|-------------|-----------|------------|-------------|-----------|----------|-----------|---------------|-------------|---------------|-------------|---------|
| Par | MODEL | 3-phase | A2001-A | A2002-A | | | A2015-A | A2022-A | A2037-A | A4002-A | A4004-A | A4007-A | A4015-A | A4022-A | A4037-A |
| Numb | • | Single-phase | | | | | AB015-A | - | - | - | - | - | - | - | - |
| | Max. Applic | | 0.13 | 0.25 | 0.5/.75 | 1 | 2 | 3 | 5 | 0.5 | 1 | 1.5/2 | 3 | 3.5 | 5 |
| ľ | Notor Output*1 HP (kW) | | (0.1) | (0.2) | (0.4) | (0.75) | (1.5) | (2.2) | (3.7) | (0.2) | (0.4) | (.75) | (1.5) | (2.2) | (3.7) |
| | • | pacity (kVA) | 0.3 | 0.6 | 1.1 | 1.9 | 3.0 | 4.2 | 6.7 | 0.9 | 1.4 | 2.6 | 3.7 | 4.2 | 6.5 |
| Output Characteristics | | t Current (A) | 0.8 | 1.6 | 3 | 5 | 8 | 11 | 17.5 | 1.2 | 1.8 | 3.4 | 4.8 | 5.5 | 8.6 |
| tput | | | | | | | | | | | | | | | |
| 0n arac | Max. Output Voltage (V) | | 3-phase, 200 to 230 V (proportional to input voltage) 3-phase, 380 to 460 V (proportional to input voltage) | | | | | | | | | | ige) | | |
| చ్ | Max. Output Frequency (Hz) | | 400 Hz (Programmable) | | | | | | | | | | | | |
| <u>></u> | Rated Input Voltage | | 3.nhasa 200 to 230 V 50/60Hz | | | | | | | | | | | | |
| Supply | and Frequency | | Single-phase, 200 to 240 V, 50/60Hz Single-phase, 200 to 240 V, 50/60Hz | | | | | | | | | | | | |
| ver | Allowable Voltage Fluctuation | | | | | | | | | | | | | | |
| Power | Allowable Frequency Fluctuation | | | | | | | | | | | | | | |
| | Control Method | | Sine wave PWM (V/f control) | | | | | | | | | | | | |
| | Frequency Control Range | | 0.1 to 400 Hz | | | | | | | | | | | | |
| | Frequency Accuracy | | Digital reference: ±0.01% 14 to 122°F (-10 to +50°C) | | | | | | | | | | | | |
| S | (Temperature Change) | | Analog reference: ±0.5% 59 to 95°F (25±10°C) | | | | | | | | | | | | |
| eristi | Frequency Setting | | Digital reference: 0.01 Hz (less than 100 Hz)/1 Hz (100 Hz or more) | | | | | | | | | | | | |
| acte | Resolution | | Analog reference: (0:06/60 Hz) equivalent to 1/1000 of max. output frequency | | | | | | | | | | | | |
| Char | Output Frequency Resolution | | | | | | | | | | | | | | |
| <u>lo</u> | Overload Capacity Frequency Reference Signal | | 150% rated output current for one minute | | | | | | | | | | | | |
| Control Characteristics | Accel/Decel Time | | 0 to 10 VDC (20 kΩ), 4 to 20 mA (250 Ω), 0 to 20 mA (250 Ω) frequency setting volume (selectable) | | | | | | | | | | | | |
| | Braking Torque | | 0.1 to 999 sec. (accel./decel. time are independently programmed) Short-term average deceleration torque*2 0.13 HP, 0.25 HP: 150%; 0.5 HP, 1 HP: 100%; 2 HP: 50%; 3 HP or more: 20% | | | | | | | | | | | | |
| | | | Continuous regenerative torque: Approx. 20% | | | | | | | | | | | | |
| | V/f Characteristics | | Possible to program any V/f pattern | | | | | | | | | | | | |
| | Motor Overload Protection | | Electronic thermal overload relay | | | | | | | | | | | | |
| | Instantaneous | Motor coasts to a stop at approximately 250% of inverter rated current | | | | | | | | | | | | | |
| | Overload | | Motor coasts to a stop after 1 minute at 150% of inverter rated output current | | | | | | | | | | | | |
| S | Overvoltage | | Motor c | oasts to a | stop if D | C bus vol | ltage exce | ed 410 V | | Motor coa | asts to a sto | p if DC bus | s voltage exc | ceeds 820 \ | / |
| Protective Functions | Undervoltage | | Stops when DC bus voltage is approximately 200 V or less Stops when DC bus voltage is approximately 400 V or less | | | | | | | | | | | | |
| oun ₋ | | | (approx. 160 V or less for single-phase series) | | | | | | | | | | | | |
| ive | Momentary Power Loss | | Stops if power loss is 15 ms or more. By setting inverter, operation can be continued if power is | | | | | | | | | | | | |
| tect | Cooling Fin Overheat | | restored within approximately 0.5 s | | | | | | | | | | | | |
| Prc | Cooling Fin Overheat | | Protected by electronic circuit | | | | | | | | | | | | |
| | Stall Prevention Level | | Individual levels during acceleration/running, enable/disable provided during deceleration Protected by electronic circuit (fan-stalling detection) | | | | | | | | | | | | |
| | Cooling Fan Fault Ground Fault | | Protected by electronic circuit (ran-stailing detection) Protected by electronic circuit (rated output current level) | | | | | | | | | | | | |
| | Power Charge Indication | | RUN lamp stays ON or digital operator LED stays ON. (Charge LED is provided for 460 V) ON until the DC bus voltage becomes 50 V or less | | | | | | | | | | | | |
| | Cooling Me | | Cooling fan is provided for: 230 V, 1 HP (3-phase) 460 V, 2 HP (single-phase), other models are self-cooling | | | | | | | | | | | | |
| Enclosure Ambient Temperature | | | Open chassis IP20 | | | | | | | | | | | | |
| | | | Open chassis: 14 to 122'F (-10 to +50'C) (not frozen) | | | | | | | | | | | | |
| ta ° | Humidity | | | or less (| | | -, (| | | | | | | | |
| Environmental Conditions | Storage Temperature*3 | | | 0°F (-20 t | | | | | | | | | | | |
| /ironr :ondit | Location | | | (free from | | e gases or | r dust) | | | | | | | | |
| Elwi CC | Elevation | | 3280 ft | (1000 m) | or less | | | | | | | | | | |
| | Vibration | | Up to 9.8 m/S2 (1 G) at less than 20 Hz, up to 2 m/S2 (0.2 G) at less than 20 to 50 Hz | | | | | | | | | | | | |
| | Wiring Dist | 328 ft (* | 100 m) or | less betw | veen Inve | rter and N | 1otor | | | | | | | | |
| | Multi-function Input | | Four of the following input signals are selectable: Reverse run (3-wire sequence), fault reset, external fault (NO/NC contact input), | | | | | | | | | | | | |
| | | | multi-step speed operation, Jog command, accel/decel time select, external baseblock (NO/NC contact input), speed search | | | | | | | | | | | | |
| Other Functions | | | command, accel/decel hold command, LOCAL/REMOTE selection, communication/control circuit terminal selection, emergency stop fault, emergency stop alarm. | | | | | | | | | | | | |
| | Multi-function Output | | Following output signals are selectable (1 NO/NC contact output): Fault, running, zero speed, at frequency, frequency detection | | | | | | | | | | | | |
| | | | (output frequency ≤ or ≥ set value), during overtorque detection, minor error, during baseblock, operation mode, inverter run | | | | | | | | | | | | |
| Other | | | ready, during fault retry, during under-voltage, during speed search, data output through communication. | | | | | | | | | | | | |
| 0 | | | Full-range automatic torque boost, slip compensation, DC injection braking current/time at start/stop frequency reference bias/gain, frequency reference with built-in potentiometer, MEMOBUS communications (RS-485/422, max. 19.2 K bps) capable | | | | | | | | | | | | |
| | Standard | Functions | | | | nce with I | built-in po | tentiomet | er, MEMC | BUS comn | nunications | (RS-485/42 | 22, max. 19. | 2 K bps) ca | apable |
| | | | with obt | tional unit | | | | | | | | | | | |

^{*1:} Based on a standard 4-pole motor for max. applicable motor output. Select the inverter model within the allowable motor rated current *2: Shows deceleration torque for uncoupled motor decelerating from 60 Hz with the shortest possible deceleration time *3: Temperature during shipping (for short period)

Dimensions

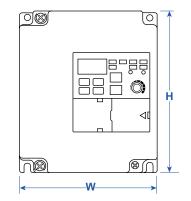
| Rated Voltage | Rated Output Current (A) | Nominal HP * | Part Number | Overall Dimensions (HXWXD) inches (mm) | Approx. Weight Ib (kg) |
|-------------------------|-----------------------------|-----------------|---------------|---|---------------------------|
| | 0.8 | 0.13 | 3G3JV-AB001-A | 5.04x2.68x2.76 (128x68x70) | 1.1 (0.5) |
| | 1.6 | 0.25 | 3G3JV-AB002-A | 5.04x2.68x2.76 (128x68x70) | 1.1 (0.5) |
| 230 VAC Single-Phase | 3 | 0.75 | 3G3JV-AB004-A | 5.04x2.68x4.41 (128x68x112) | 1.98 (0.9) |
| | 5 | 1 | 3G3JV-AB007-A | 5.04x4.25x5.08 (128x108x129) | 3.31 (1.5) |
| | 8 | 2 | 3G3JV-AB015-A | 5.04x4.25x6.06 (128x108x154) | 3.31 (1.5) |
| | 0.8 | 0.13 | 3G3JV-A2001-A | 5.04x2.68x2.76 (128x68x70) | 1.1 (0.5) |
| | 1.6 | 0.25 | 3G3JV-A2002-A | 5.04x2.68x2.76 (128x68x70) | 1.1 (0.5) |
| | 3 | 0.75 | 3G3JV-A2004-A | 5.04x2.68x4.16 (128x68x102) | 1.76 (0.8) |
| 230 VAC 3-Phase | 5 | 1 | 3G3JV-A2007-A | 5.04x2.68x4.8 (128x68x122) | 1.98 (0.9) |
| | 8 | 2 | 3G3JV-A2015-A | 5.04x4.25x5.08 (128x108x129) | 2.83 (1.3) |
| | 11 | 3 | 3G3JV-A2022-A | 5.04x4.25x6.06 (128x108x154) | 3.31 (1.5) |
| | 17.5 | 5 | 3G3JV-A2037-A | 5.04x5.04x6.34 (128x128x161) | 4.63 (2.1) |
| | 1.2 | 0.5 | 3G3JV-A4002-A | 5.04x2.68x3.19 (128x108x81) | 2.20 (1.0) |
| | 1.8 | 1 | 3G3JV-A4004-A | 5.04x4.25x3.90 (128x108x99) | 2.42 (1.1) |
| 460 VAC | 3.4 | 2 | 3G3JV-A4007-A | 5.04x4.25x5.08 (128x108x129) | 3.31 (1.5) |
| 3-Phase | 4.8 | 3 | 3G3JV-A4015-A | 5.04x4.25x6.06 (128x108x154) | 3.31 (1.5) |
| | 5.5 | 3.5 | 3G3JV-A4022-A | 5.04x4.25x6.06 (128x108x154) | 3.31 (1.5) |
| | 8.6 | 5 | 3G3JV-A4037-A | 5.04x5.51x6.34 (128x140x161) | 6.62 (2.1) |

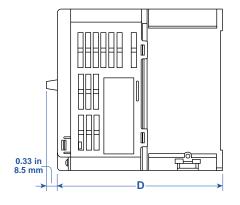




Select the inverter model within the allowable motor rated current.

Use of high efficiency motors and motors of different base speeds may increase/decrease the applicable motor HP.





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^{*}Nominal HP ratings based on standard 1800 RPM motor amperage.